

ANELLO GNSS/INS EVALUATION KIT

The ANELLO GNSS/INS EVALUATION KIT is an independent, reliable and accurate navigation solution for an autonomous world.



ANELLO GNSS/INS EVK

Powered by ANELLO's unique optical gyroscope technology, the ANELLO Global Navigation Satellite System (GNSS) / Inertial Navigation System (INS) Evaluation Kit (EVK) can maintain centimeter accuracy in conditions where far more expensive reference grade systems degrade, including extended full GNSS loss operation. In addition, the system is also accurate over wide temperature ranges and under extreme vibration.

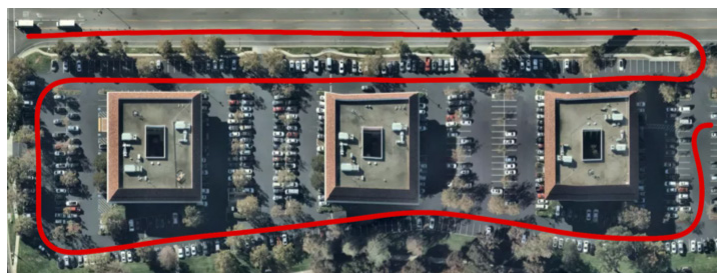


Fig. 1: ANELLO GNSS/INS EVK Data on Map

The Evaluation Kit contains everything needed to get started including the ANELLO GNSS/INS, two dual-band GNSS antennae, and cables.

ANELLO PYTHON PROGRAM

ANELLO provides an open-source Python tool for configuration, logging, NTRIP relay, and plotting data.

GPS: ON		LOG: OFF		Last GPS (s): 0.27		ANELLO	
<small>INS IMU MAP</small>							
Lat. (deg):	37.3991189	Lon. (deg):	-121.979278				
Altitude (m):	-17.09	Heading (deg):	0.00				
Roll (deg):	0.18	Pitch (deg):	2.87				
Speed (m/s):	0.000	State:	Stationary				
Solution:	INS (Pos. Only)	Num Sats:	8				
Carrier Soln:	No solution	GPS Fix:	3D-Fix				

Fig. 2: Python Tool Monitor

FEATURES

Reference-grade 200Hz Position, Velocity, and Attitude

< 0.5°/Hr Un-aided Heading Drift

Accurate in severe multipath and GNSS denied

Dual 184-channel five constellation dual-band GNSS receivers

GPS, Glonass, Galileo, Beidou (Compass), QZSS

Reliable Autonomous Land Vehicles, Advanced ADAS Systems

Precise Heavy Equipment and Machine Control

Convenient and Fast Setup

TECHNICAL SPECIFICATIONS (COMMERCIAL)

Solution Accuracy¹

Horizontal Position Accuracy	
SPS	1.2 m cep
RTK ²	0.02 m cep
60s GNSS Outage³	< 1.0 m rms
Velocity Accuracy	0.01 m/s rms
Heading Accuracy ⁴	0.2° rms
Attitude Accuracy (Roll/Pitch)	0.02° rms

IMU Performance

Optical Gyroscope (Heading/Z-Axis)		
Range	200°/s	
Bias Instability	< 0.5°/hr	
Angle Random Walk	< 0.05°/√hr	
MEMS IMU (6-Axis)	Accelerometer	Gyroscope
Range	8g	up to 400°/s
Bias Instability	20ug	1.5°/hr
Random Walk	0.03m/s/√hr	0.3°/√hr

GNSS & Timing

Signal Bands	L1 C/A, L2C, L1OF, L2OF, B1I, B2I, E1, E5b and SBAS
RTK Initialization Time	< 1 min, using RTCM3 corrections
Output Data Rate	200 Hz

Environment

Operating Temperature	-40 to +70°C
Vibration	IEC 60068-2-6 (5g)
Shock Survival	MIL-STD-810G (40g)

Electrical

Input Voltage	8 to 30 VDC
Power Consumption	4 W typical
Digital Interface	Ethernet, USB/Serial

Physical

Size	4.2" x 1.5" x 5.0"
Weight	1 lbs.

Notes:

1. After Initialization
2. < 20km Baseline from Base
3. Additional Drift Post NSS Loss, with Wheel Speed Aiding
4. Properly Installed Antennae