



# **SCOUT-M2X**

The **SCOUT-M2X** is the ideal combination of performance, flexibility and affordability. It brings a new level of precision and accuracy to the long trusted SCOUT lineup of multi-channel mapping scanners.

Long range, high pulse rate and triple return capability allow for UAV acquisitions of more data faster through vegetation. Dense survey data can be collected by nearly any method; UAV, Mobile, Backpack, and more. The **SCOUT-M2X** is also SLAM capable, taking you where others cannot.

### **FEATURES**

- Fast and accurate measurements with a 640 kHz pulse rate scanner
- · Live control and feedback during acquisition, including Phoenix's signature real-time point cloud
- SLAM (Simultaneous localization and mapping) capable
- Integrated high resolution camera options up to 61 MP

### **QUICK SPECS**

#### ABSOLUTE ACCURACY

2 - 4 cm RMSEz @ 100 m AGL(1)(2)(4)

#### INTRASWATH PRECISION

4 cm RMSDz @ 100 m AGL(1) (2) (3)

#### WEIGHT

1.8 kg (without camera)

#### **PULSE RATE**

640 kHz. up to 3 returns

### LINE RATE

10 Hz

# **PLATFORM**

OVERALL DIMENSIONS*	17.7 x 11.6 x 12.3 cm
OPERATING VOLTAGE	12 - 28 V DC
OPERATING TEMPERATURE	0° - 40° C / 32° - 104° F
POWER CONSUMPTION*	~30 W
WEIGHT*	1.8 kg
*Without Accessories	

### **LIDAR SENSOR**

LASER PROPERTIES	905 nm Class 1 (eye safe)
RANGE MAX	300 m (80 m @ 10% for all channels)
RANGE MIN	0.5 m
NUMBER OF LASERS	32
PULSE RATE	640 kHz
LINE RATE	10 Hz
VERTICAL FIELD OF VIEW	40.3° (-20.8° to +19.5°)
VERTICAL RESOLUTION	1.3°
HORIZONTAL FIELD OF VIEW	360°
MULTIPLE ECHOES	3
LASER BEAM FOOTPRINT H X V	19 cm x 22 cm @ 80m, 24 cm x 27cm @ 100 m, 28 cm x 33 cm @ 120 m

# **NAVIGATION SYSTEM**

CONSTELLATION SUPPORT	GPS+GLONASS+BEIDOU +GALILEO
SUPPORT ALIGNMENT	Kinematic, Dual-Antenna
POSITION ACCURACY	1 cm + 1 ppm RMS horizontal
ACCURACY ATTITUDE(5)	
ROLL, PITCH	0.003° RMS
HEADING	0.010° RMS

## **APPLICATIONS**



CONSTRUCTION SITE SURVEYING



AGRICULTURE & FORESTRY MONITORING



OPEN PIT MINING OPERATIONS



STOCKPILE VOLUMETRICS



TIT GENERAL MAPPING

<sup>(1)</sup> Approximate values based on PLS test condition.

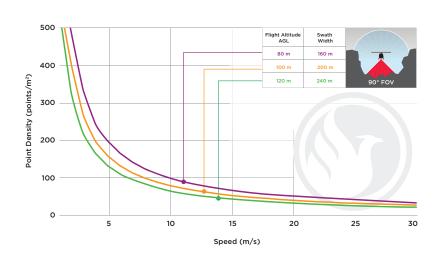
<sup>(2)</sup> Using a 90° downward field of view.

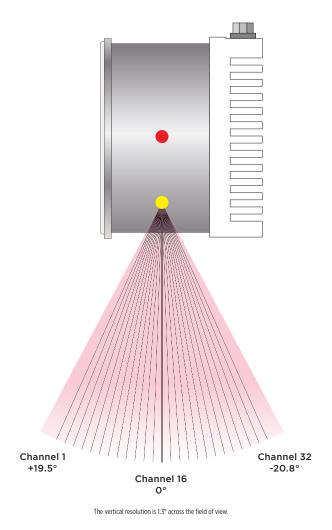
<sup>(3)</sup> Expected RMSEz when following the PLS recommended acquisition & processing workflow and ASPRS check point guidelines.

<sup>(4)</sup> Range of elevation values on flat surfaces with >20% reflectivity at the laser's wavelength. (5) Estimated post processed accuracy with IMU-25.



# **SCOUT-M2X POINT DENSITY**

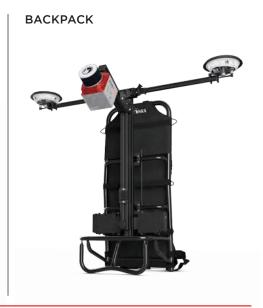




# **SCOUT-M2X OPTIONS & MOUNTS**







# EXPLORE A PHOENIX LIDAR SYSTEM FOR YOUR TEAM, CONTACT US!

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