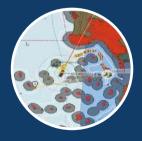


Excellent ship design as low acoustic interference from propeller and water gushes, high-quality survey data acquisition.



**Near Shore** 

**Wind Farm** 

Higher accuracy autonomous navigation algorithm for accurate site survey and higher survey efficiency.



Advanced collision avoidance system, situational awareness maximized, enables safer operations.



Anti-rolling and wave-piercing hull design, super stable even in turbulent waves and able to operate in high-sea conditions with greater weather tolerance.



Smart auto-winch structure supports equipment tow service and foldable lifter protect the wet-ends of the sensors.

## **SPECIFICATIONS**

num Alloy
e Catamaran Hull
)*2.8m(W)*3m(H)
peed 10kn
Speed 5kn
0nm
ate II
ate IV
ard propeller*2, Outboard Diesel Engine*2
sel, Tank fuel 150L×2
n Battery
e-extended by Diesel Generator
n Marine Generator with
e speed engine
/inch
fting mechanism: wet-end Lifter
nmental monitoring sensor, air cooling system
( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( )

## **COMMAND & CONTROL**

Communication	Private Network 10km
	Option: Radio, Satcoms
	Remote Control 500km
Control Station	Semi-rugged / Rugged laptop
	Industrial Smart Remote Controller
Auto Navigation &	OceanAlpha Navigation &
Auto Route Plan	Monitoring Software
Collision Avoidance System	Side light / AIS / Navigation Radar / 4*HD camera
Auto Homing	$\sqrt{}$
Smart Launch & Recovery	$\checkmark$

<sup>\*</sup> Planned maintenance of engine \*400 hours

## PAYLOAD INTEGRATION ABILITY

MBES: Teledyne T20 / T50 / Kongsberg EM2040P MKII Sub-bottom Profiler: Innomar / Edgetech / GeoPulse Side Scan Sonar: Edgetech 4205/6205, PING 3DSS-DX-450

Typical Payload Magnetometer : Seaspy2 Water Quality Sonde

ADCP, LIDAR

Tow Support: SVP / CTD / Magnetometer / Side-scan Sonar

## OCEANO

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